

Intelligent Transportation Systems

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**Imperial College
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**Development of practically-oriented student-centred
education in the field of modelling of Cyber-Physical
Systems**

Training School for Academics in Partner Countries



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Overview

- Importance of Intelligent Transportation Systems (ITS)
- The future of mobility
- Research Activities in ITS
- Educational Activities in ITS



Introduction

Motivation

- Road transportation systems account for (in the EU alone):
 - 25% of the total energy consumption, 75% of petroleum fuel consumption
 - 22000 fatalities/year
 - 18% of total GHG Emissions
 - Total cost
 - Fuel: ~ €160 B
 - Environmental effects: €176 B
 - Accidents: € 232 B
 - Congestion accounts for one work week/year per person.



Introduction

Potential solutions to traffic congestion

- Construct new roads
 - Difficult and costly to expand roads
 - Not likely to happen on a large scale
- Reduce Traffic
 - Alternative transportation means
 - Congestion charging
- Increase existing infrastructure capacity
 - **Intelligent Transportation Systems (ITS)**

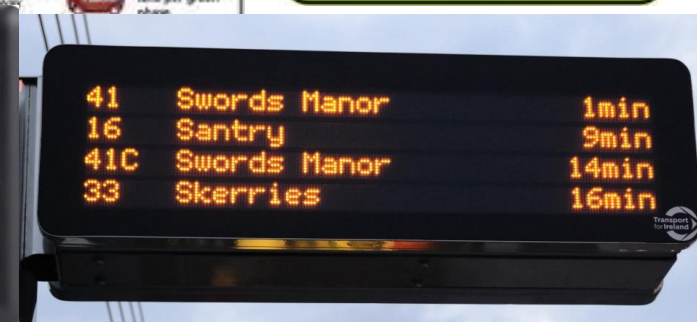


ITS application areas

- **ITS solutions** aim to reduce travel time, ease delay and congestion, improve safety, and reduce pollutant emissions by integrating electronic, sensing, information and communication technologies into the transportation system.

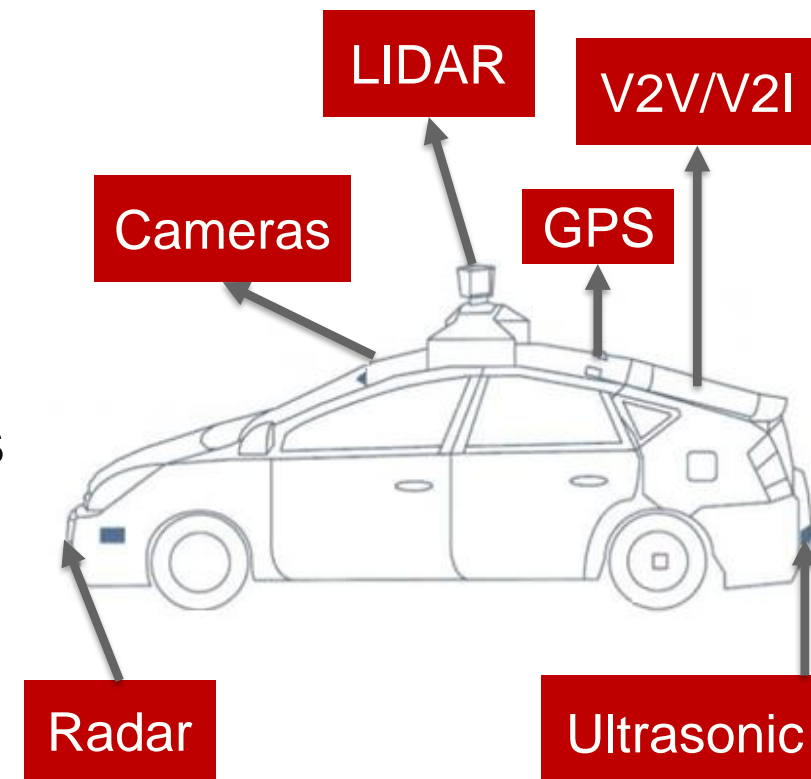
- **Main Application Categories**

- Traffic Management
- Transportation Pricing Systems
- Traveler Information
- Public Transportation
- Vehicle Control Systems



Enabling ITS technologies

- **Location-based technologies** (GPS)
 - Navigation, warning systems, estimation of vehicle-miles travelled, data collection
- **Computing Platforms** (on-board computers, smart phones)
 - Navigation, data collection, driver services
- **In-car Sensors** (radars, cameras, lidars)
 - Driver assistive systems, autonomous driving
- **Communication solutions** (V2V and V2I)
 - Cooperation between infrastructure and vehicles
- **Intelligent Software Algorithms**
 - Optimal traffic management and control, optimal navigation, intelligent vehicle control





The future of mobility

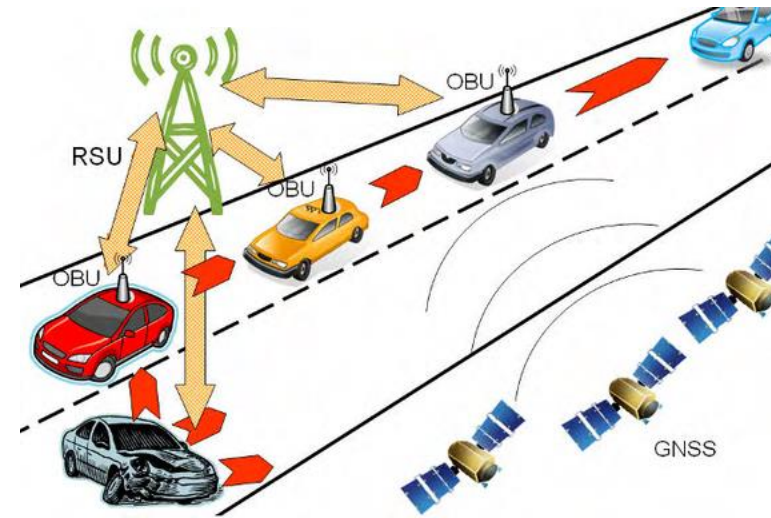
Transport revolution



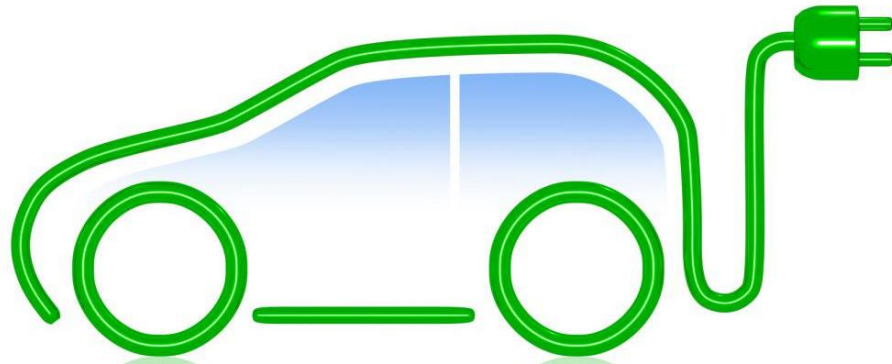
Autonomous Vehicles



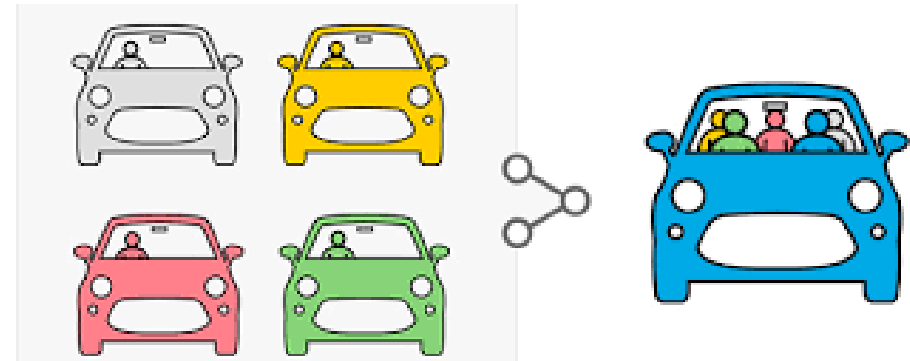
Connectivity



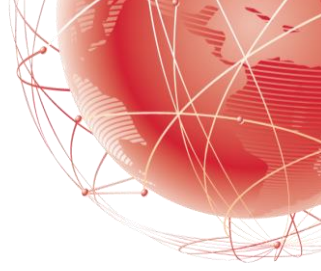
Electric Vehicles



Shared Mobility Services



Transport revolution



- Analysts claim that by 2030 95% of transport will be done by fleets of electric, connected and autonomous vehicles (**eCAVs**).

“We are on the cusp of the fastest, deepest, most consequential disruption of transportation in history”.

Source: RethinkX (independent think tank)

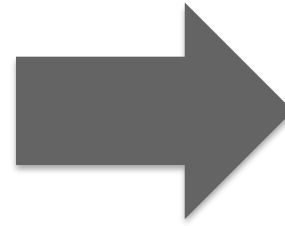
“Autonomous vehicles is the largest and most impactful industry on the planet.”

Source: Jensen Huang, NVIDIA CEO, CES 2018

Transport revolution



Individual
Car Ownership



Mobility as a
Service (MaaS)

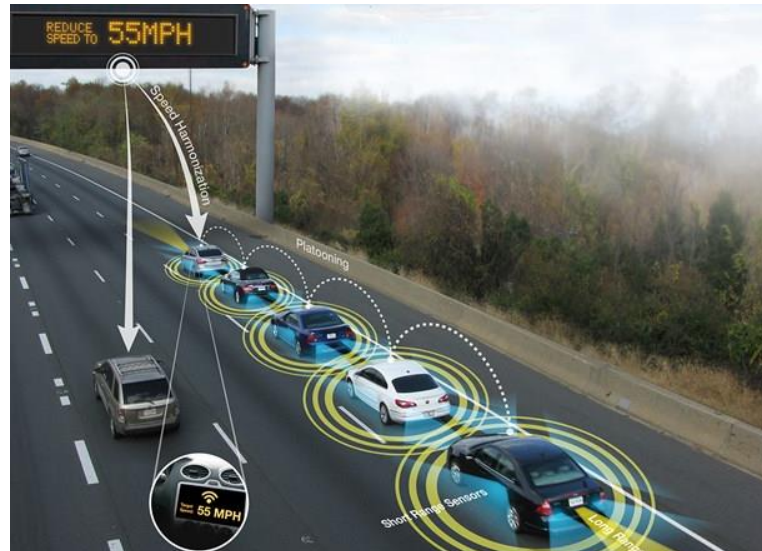
Challenges

Safety



Deadly accident of vehicle in autonomous driving mode

Traffic management



Coordination



Challenges



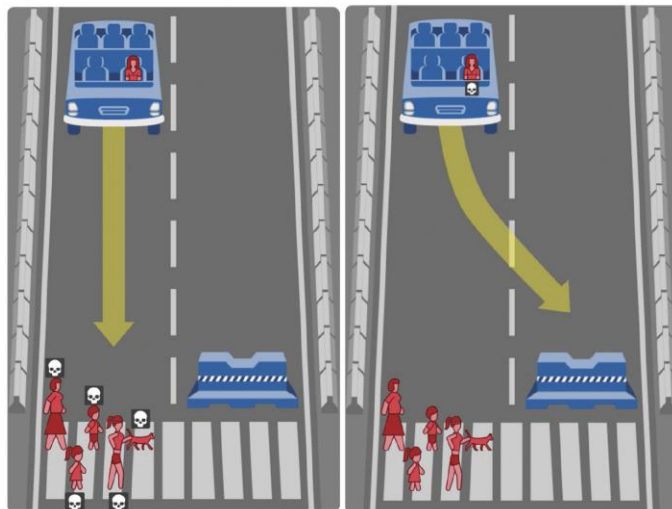
Cyber-security threats



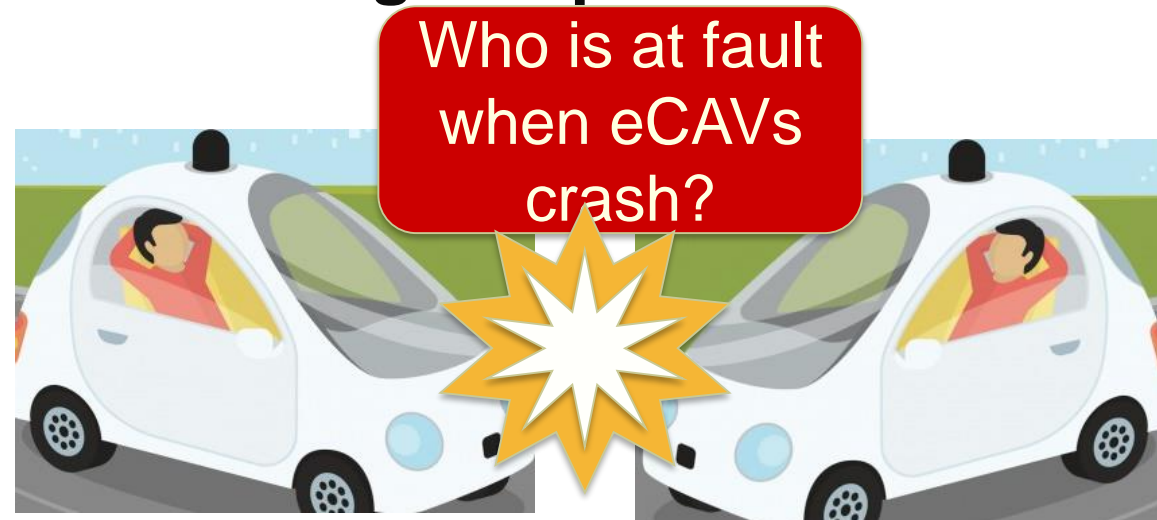
Human-Vehicle Interaction

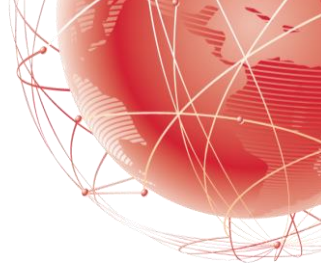


Ethical Dilemmas



Legal Implications





Research Activities in ITS

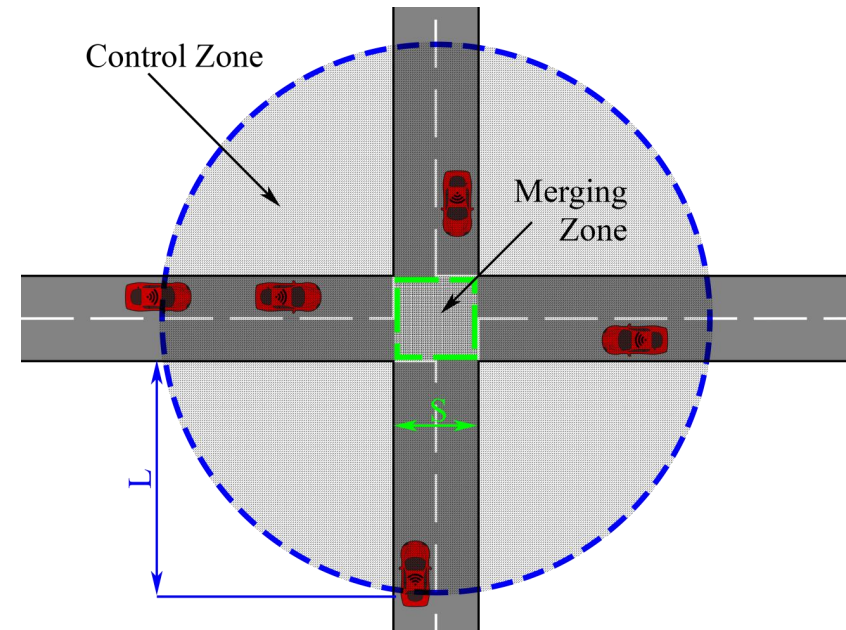
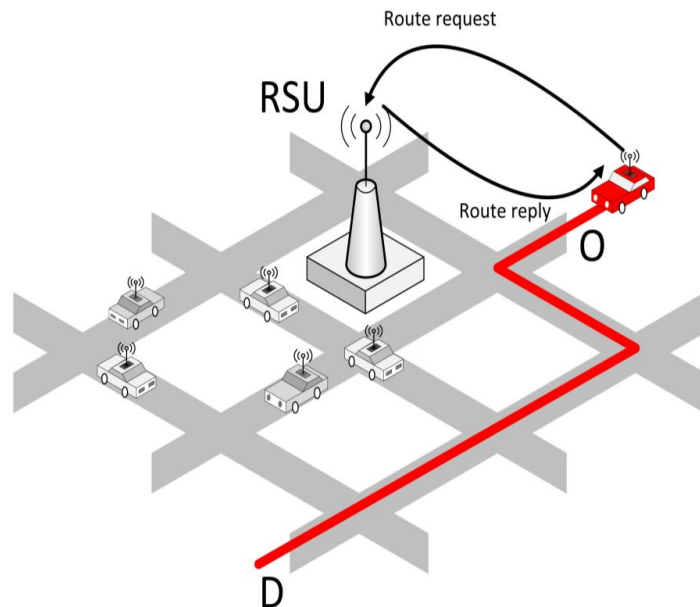
Research Directions



- Development of intelligent monitoring and control algorithms for real-time management of **contemporary** ITS:
 - Maximize efficiency and reliability
 - Estimation and prediction of the road conditions with emerging technologies
 - Traffic control strategies
 - Identifying the presence and alleviating the effects of sensors faults.
- Investigate challenges in **future** ITS
 - Involve the integration of connected and automated vehicles.
 - Develop novel architectures, protocols and algorithms for monitoring, control and security for road transportation systems.

KIOS CoE Research Contributions

- Dynamic traffic demand management and control using connected vehicles (V2I communications)
- Unsignalized intersection crossing using Connected and Autonomous Vehicles (CAVs) (V2I or V2V communications)
- Other contributions





Dynamic traffic demand management and control

Problem Statement

- **Inputs**

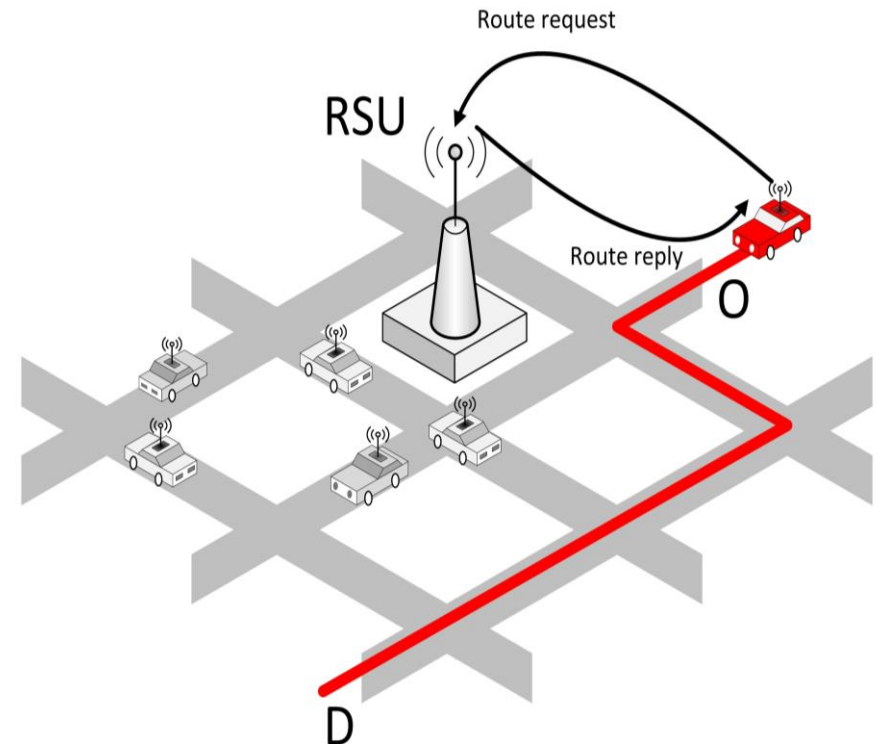
- Specific road transportation system with connected vehicles
- Vehicle requests to enter the network (time and O-D pair)

- **Objective**

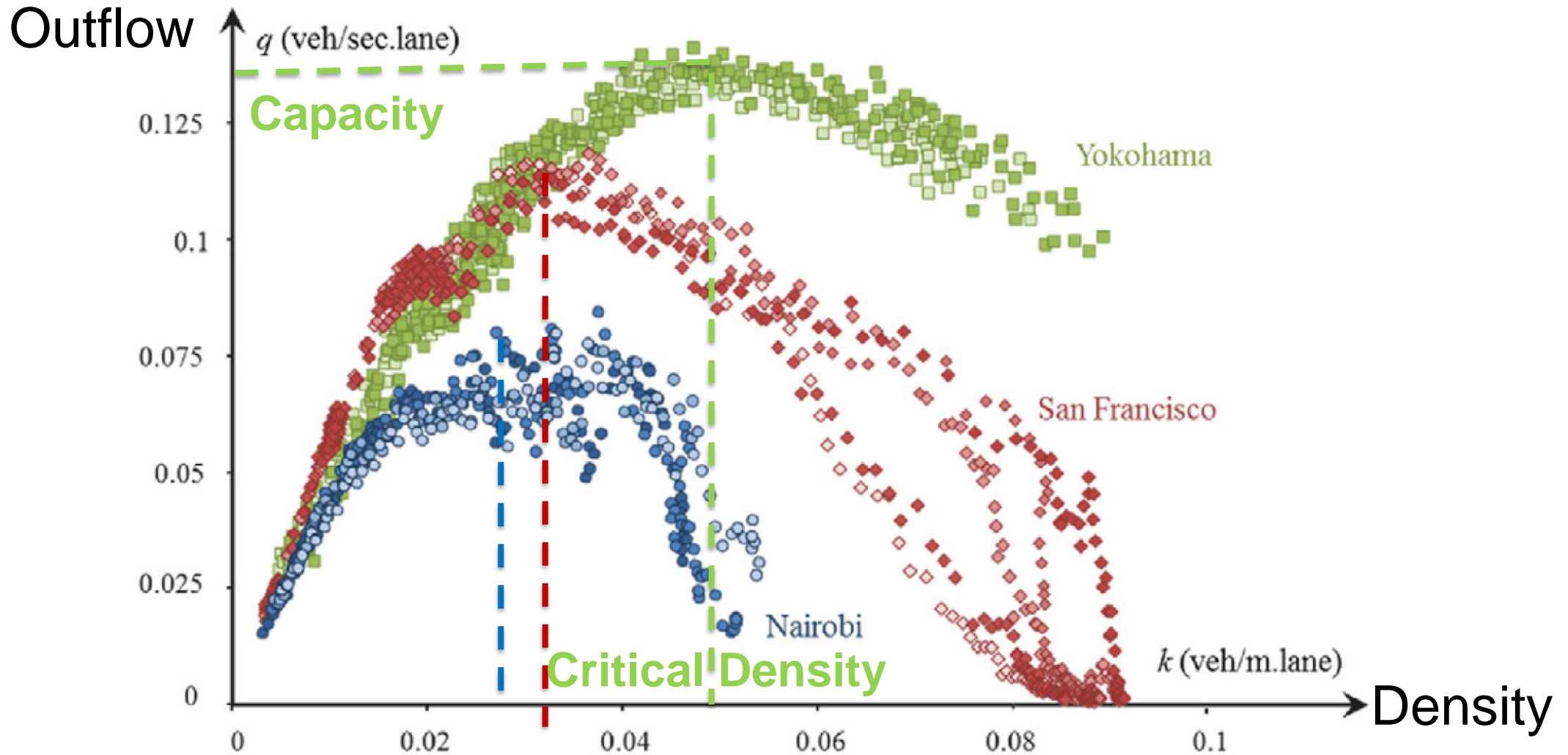
- Minimize the total travel time of all vehicles

- **Outputs**

- Route followed from each vehicles in the network

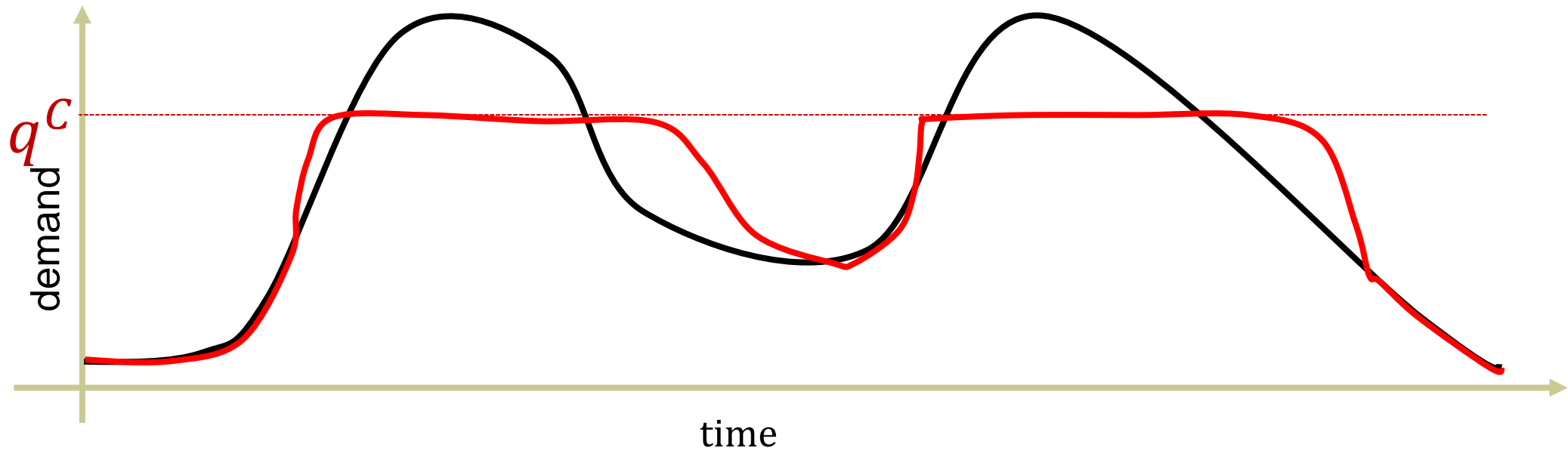


Macroscopic Fundamental Diagram



- Load vehicles in the network until the *critical density* is reached.

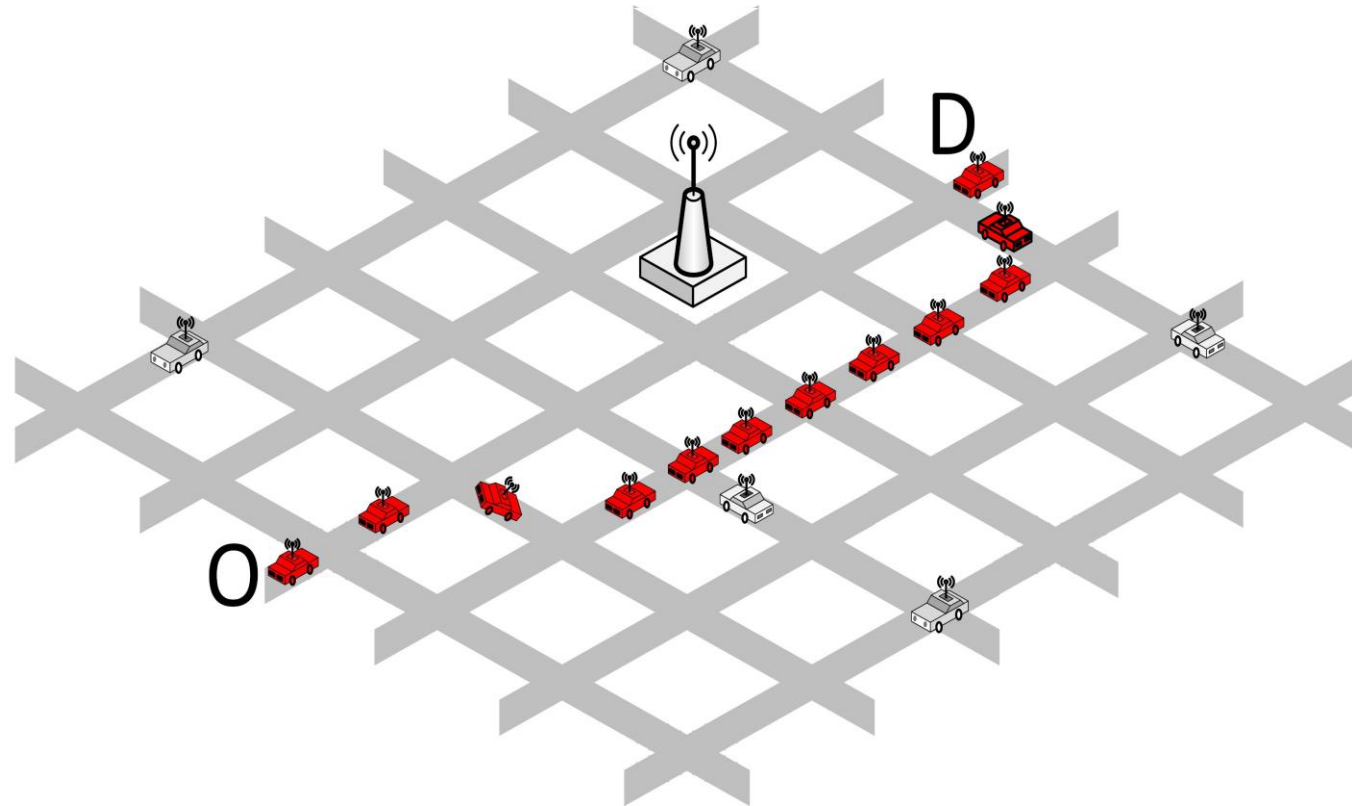
Demand Management



Traffic Demand Management

- Shift (in-time) → delay vehicles at the origin
- Shift (in-space) → utilize alternative paths

Individual vs Collective Optimum



- Routing methods should consider the benefit of the “whole” as opposed to the benefit of the individual [*]

[*] Çolak, Serdar, Antonio Lima, and Marta C. González. "Understanding congested travel in urban areas." *Nature communications* 7 (2016): 10793.

Problem Solution

Inputs

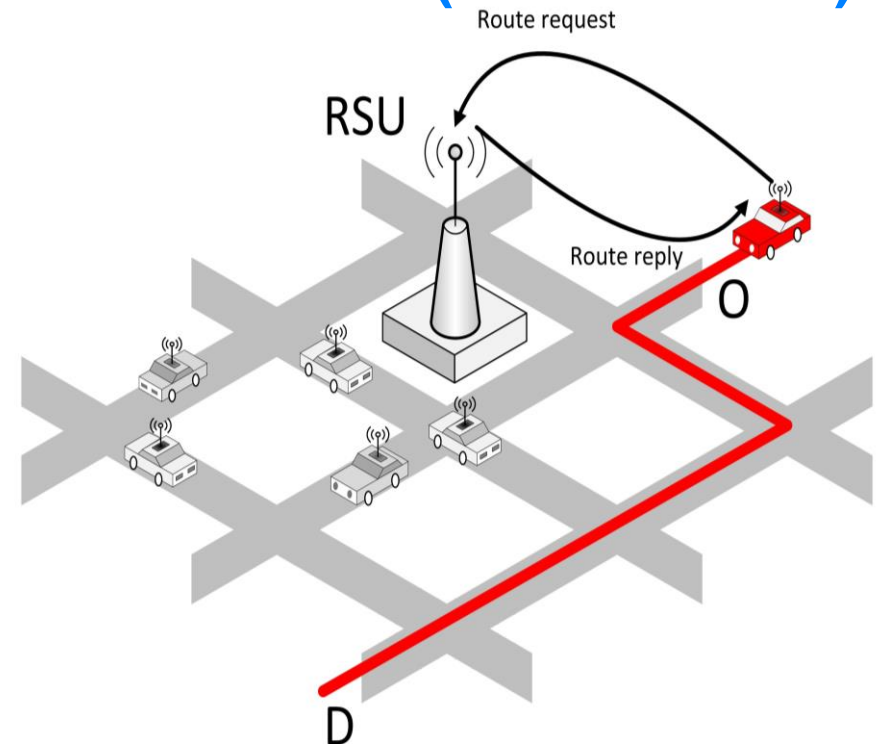
- Specific road transportation system with connected vehicles
- Vehicle requests to enter the network (time and O-D pair)
- **State of different road links at present and future times (reservations)**

Objective

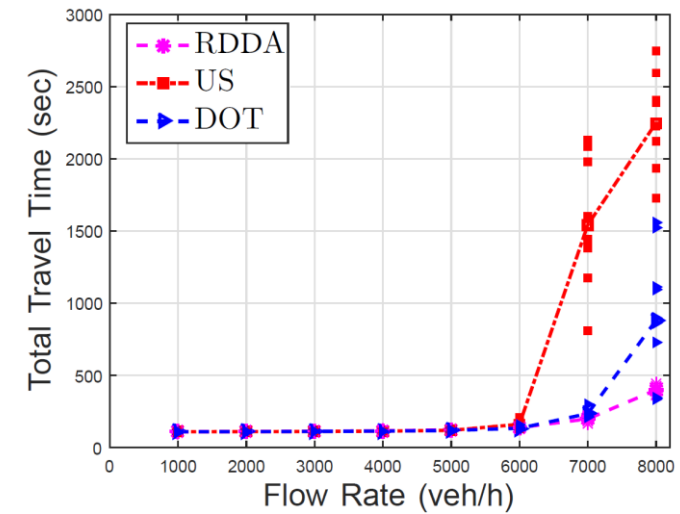
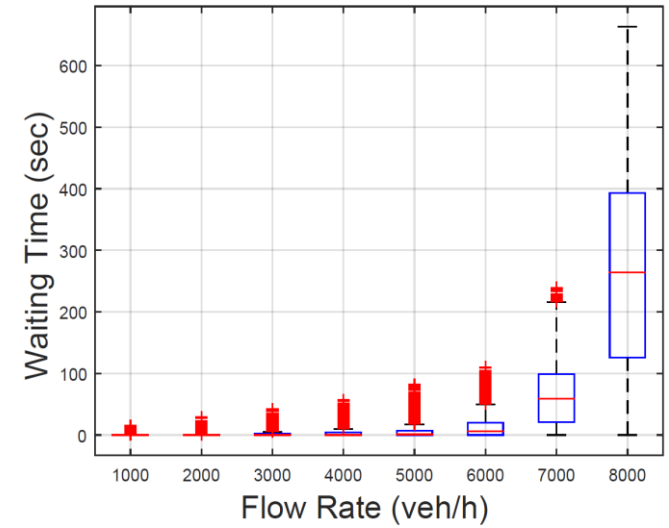
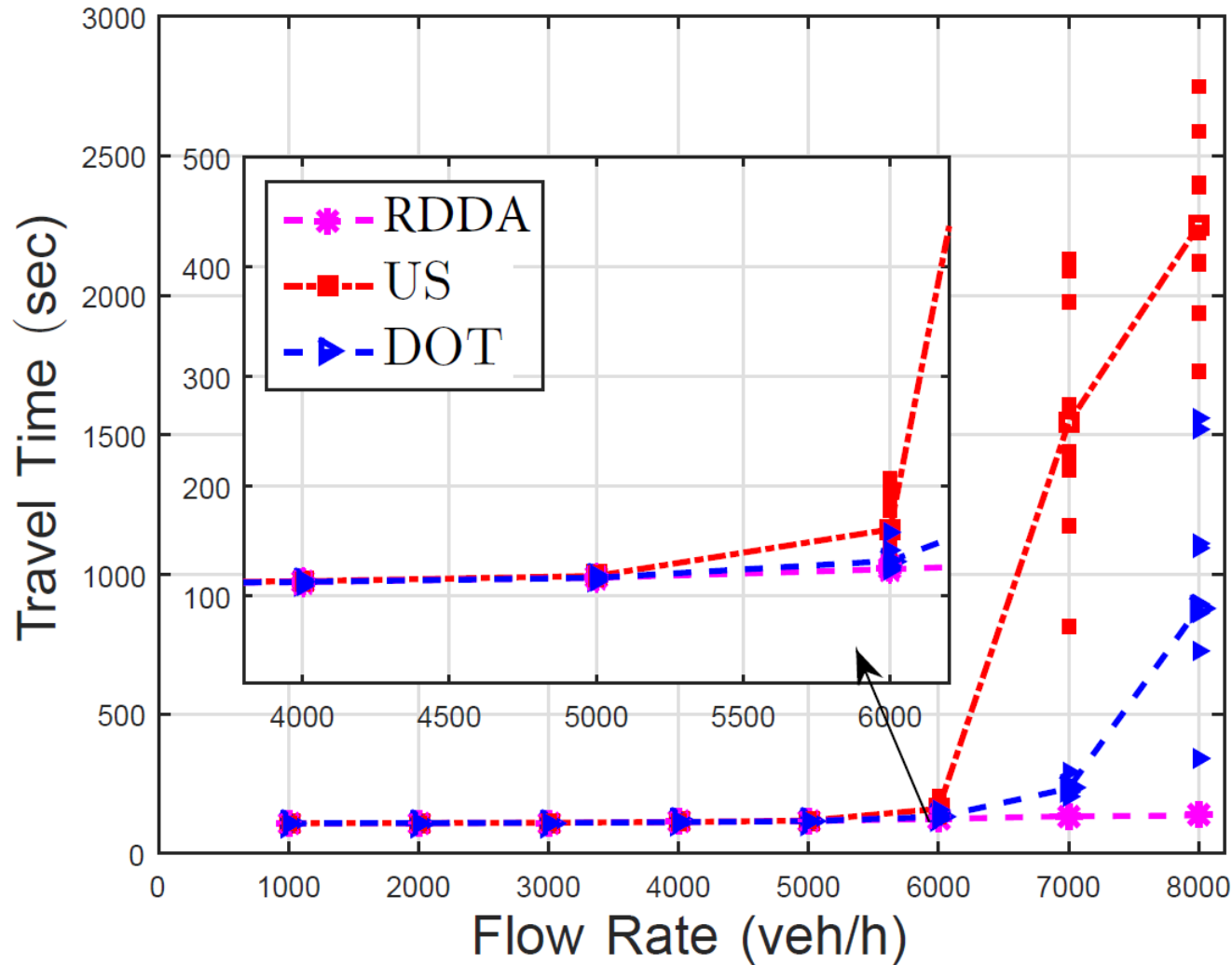
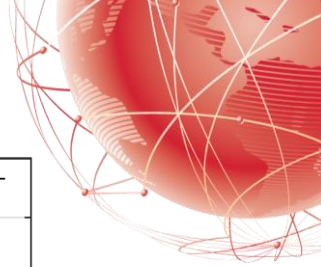
- Minimize the total travel time of all vehicles

Outputs

- Route followed from each vehicles in the network
- **Delay at the origin node for each vehicle**

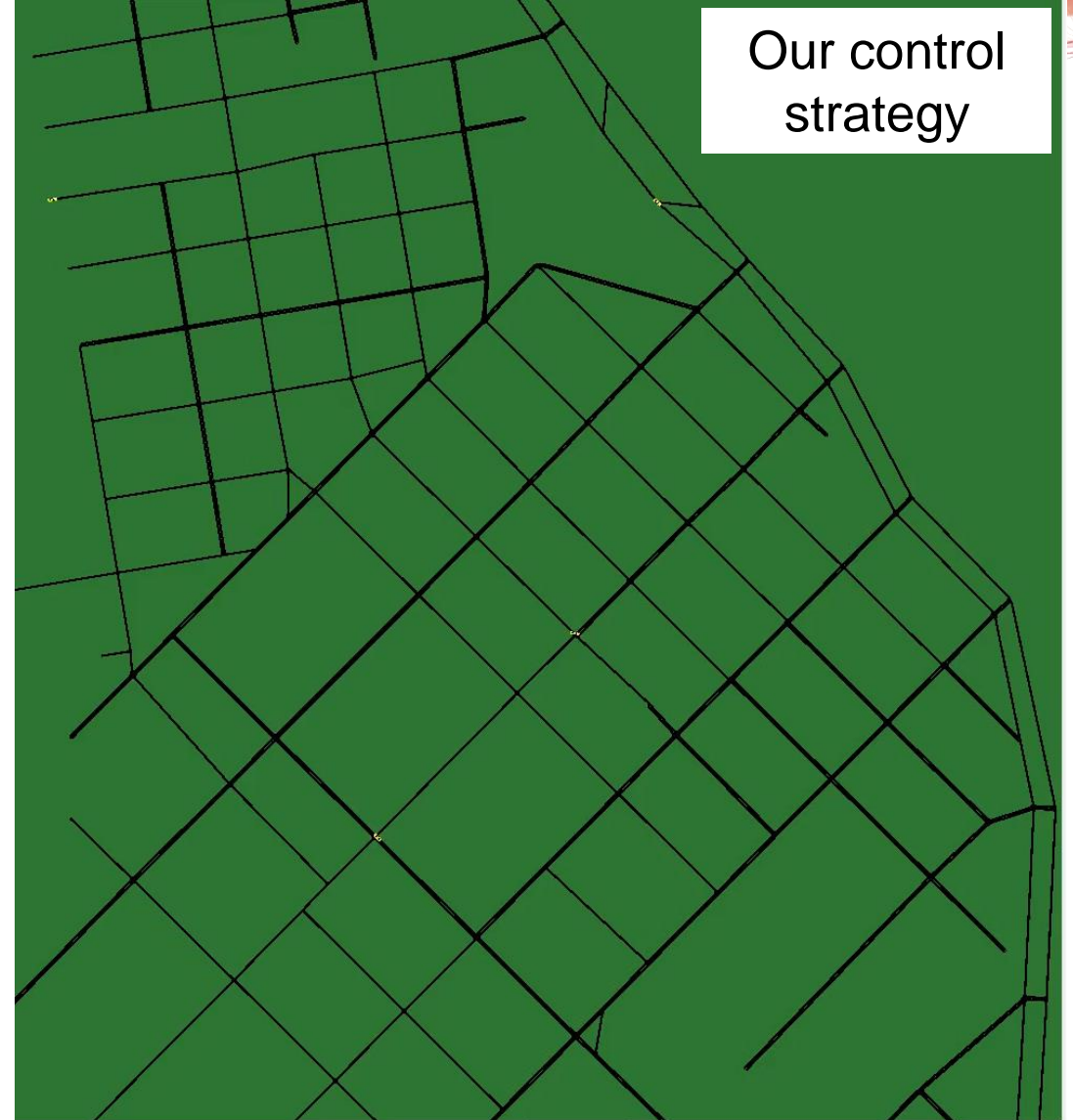
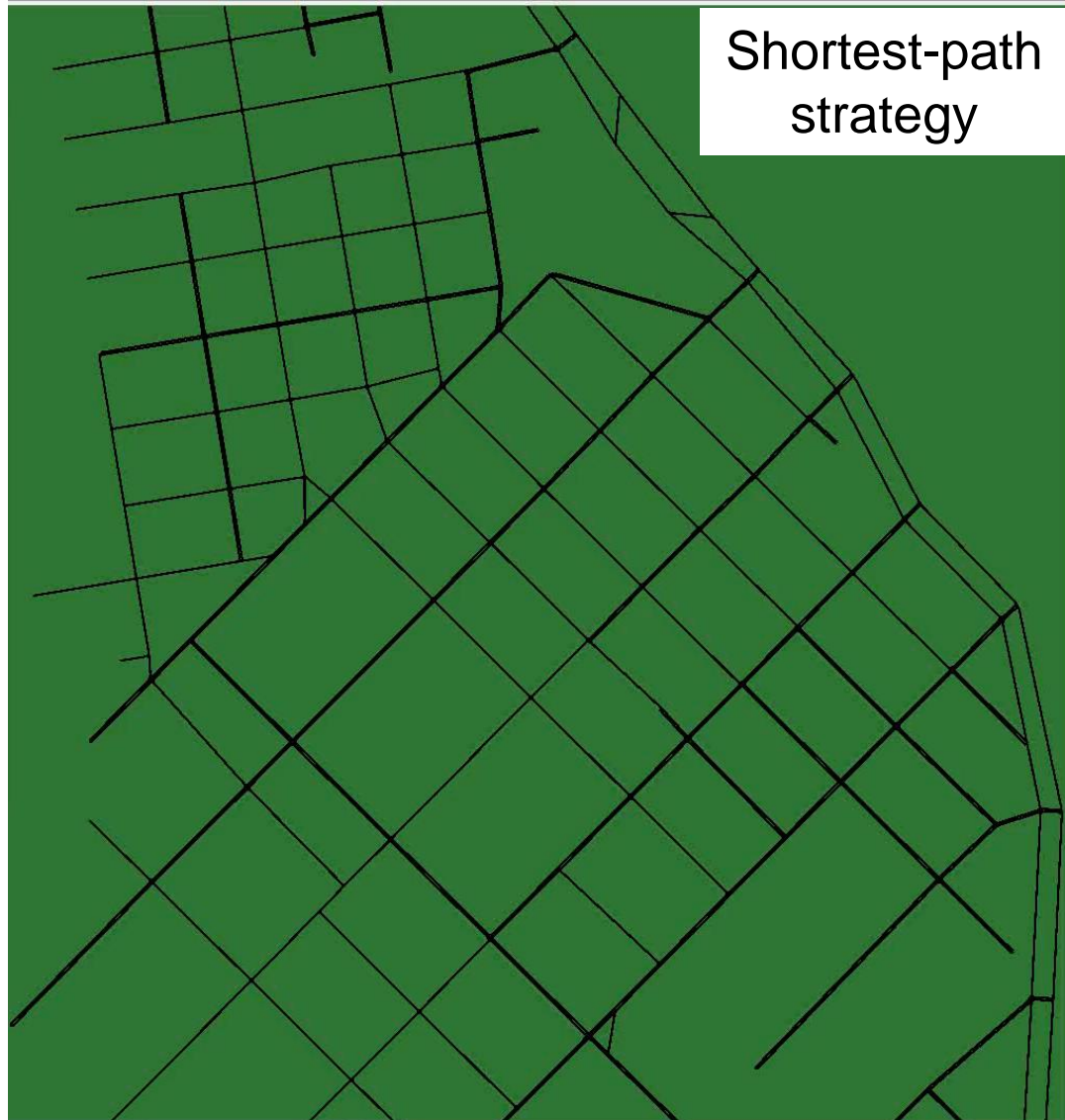


Simulation Results



Total Time = Travel Time + Waiting Time

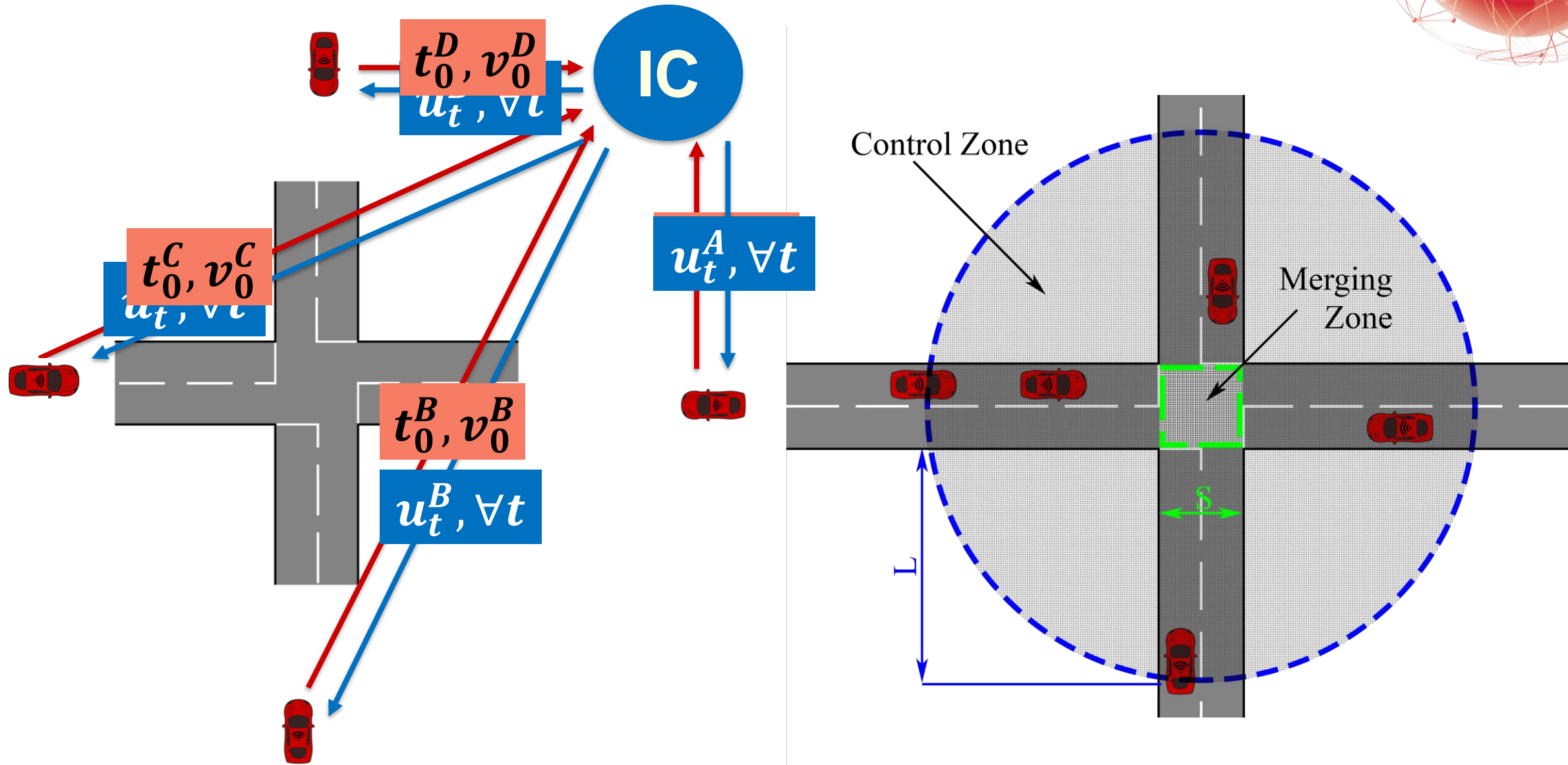
Demonstration





Unsignalized intersection crossing using CAVs

Architecture



Problem Statement

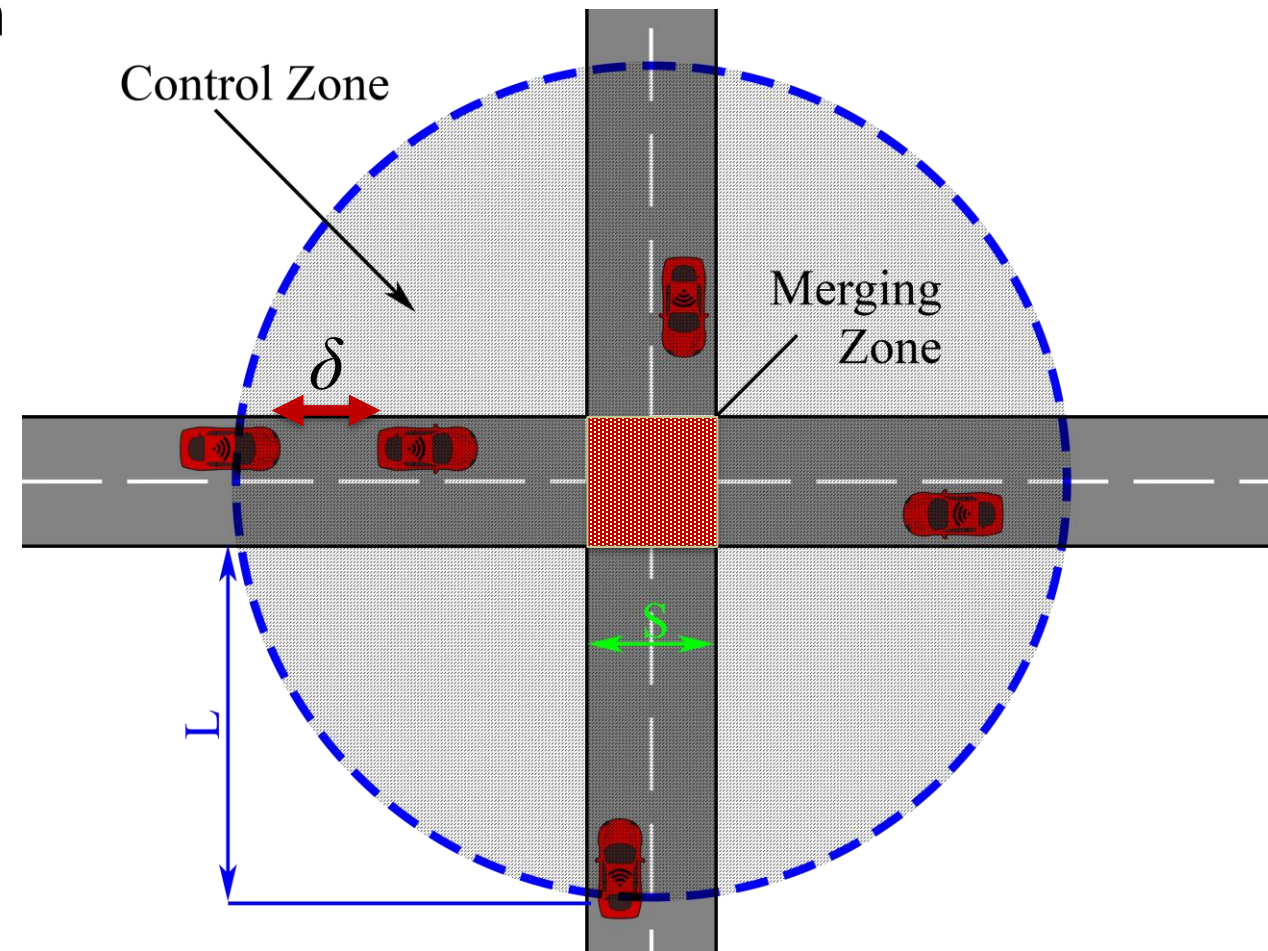
Objective: Optimize tradeoff between travel time and fuel consumption

Constraints

- Vehicle dynamics
- Lateral collision safety
- Rear-end collision safety
- Physical constraints

Assumptions

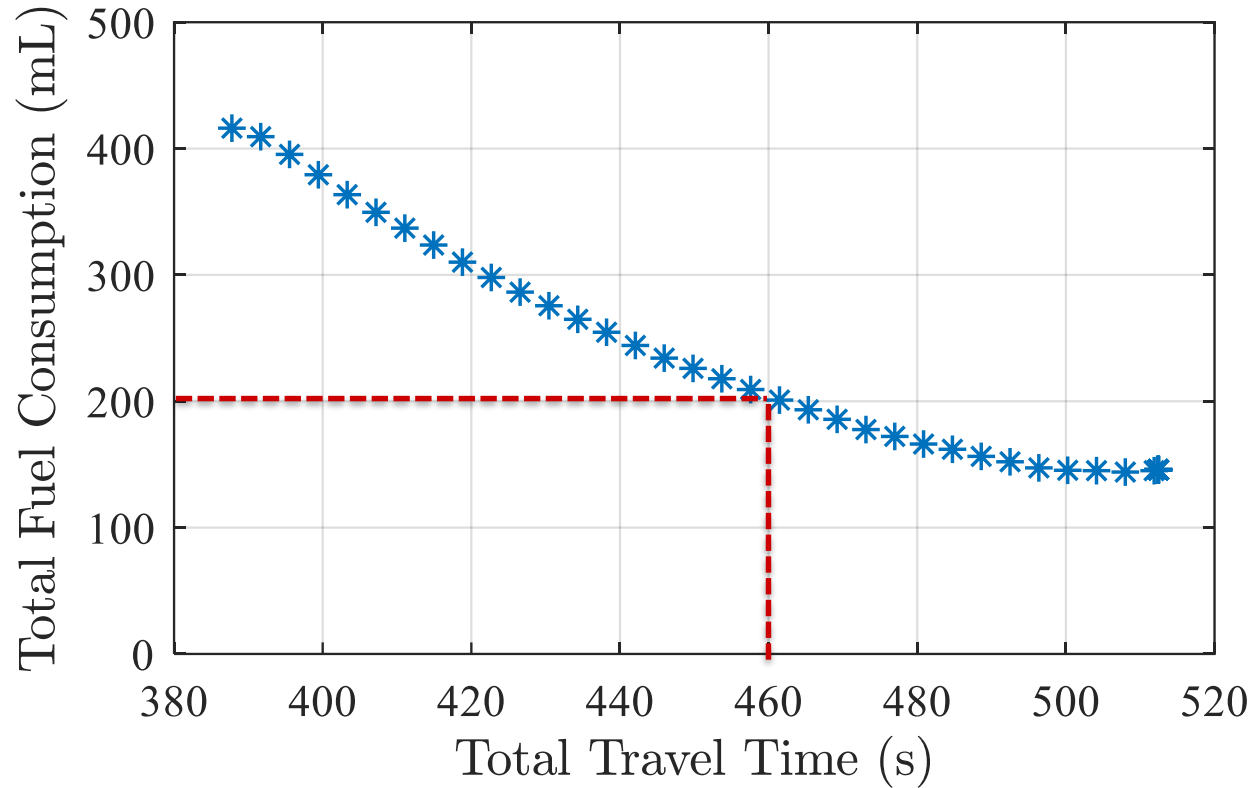
- Controller uses a FIFO Policy
- No other road users (i.e. bicycles, pedestrians)





Simulation results

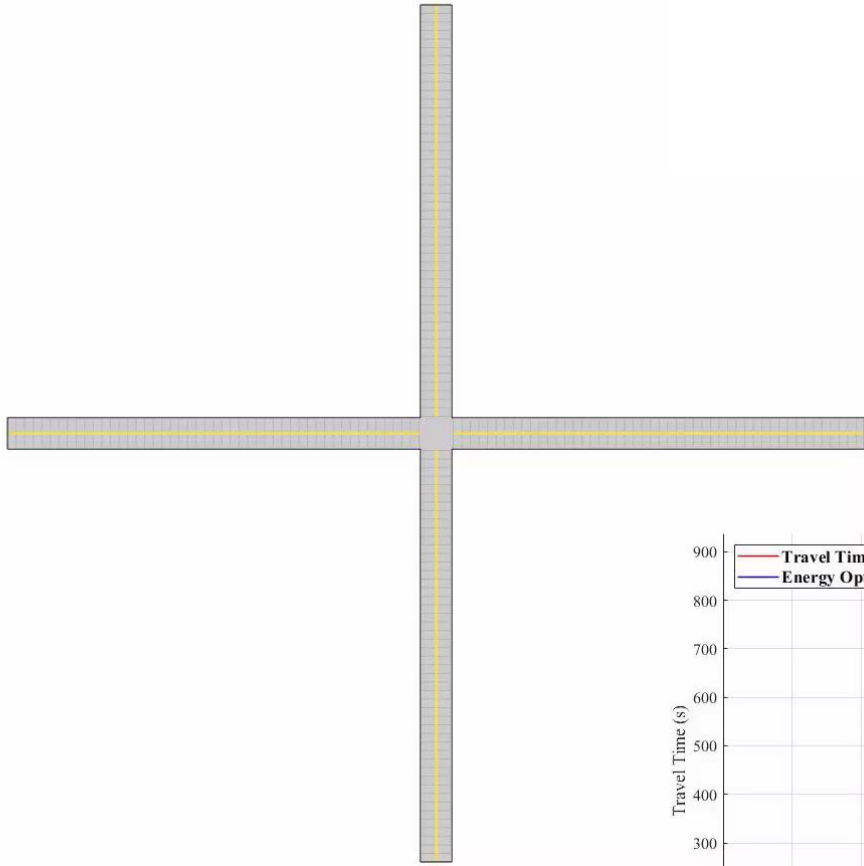
- Use of empirical fuel consumption metamodel



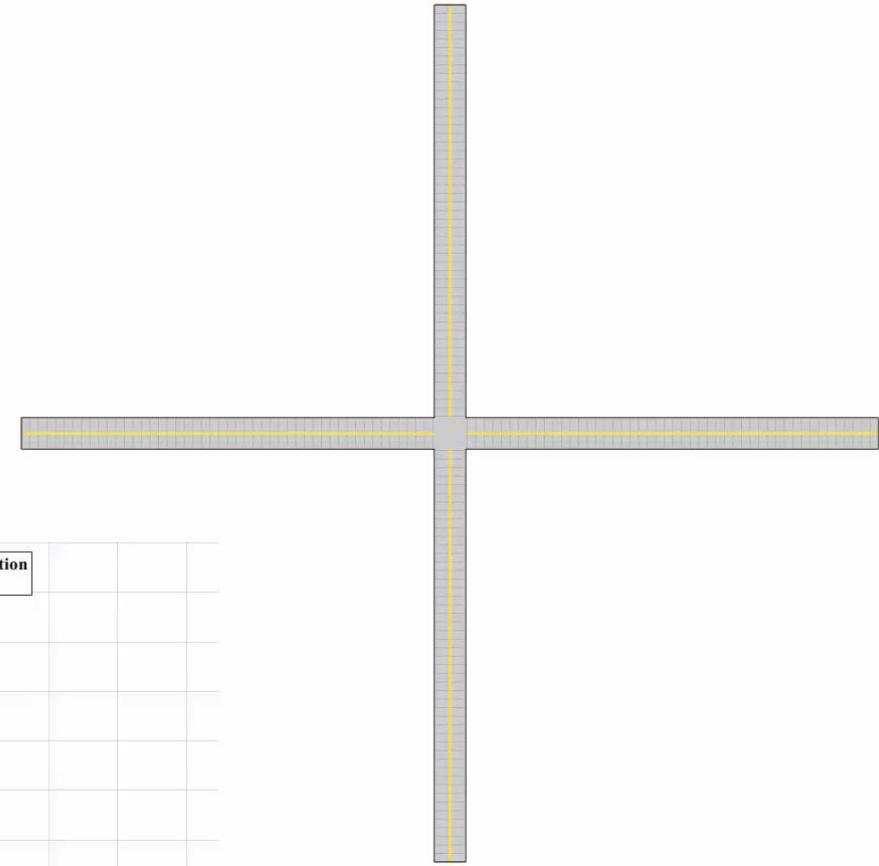
- Increase in travel time of 20% leads to a 50% reduction in fuel consumption

Autonomous Intersection Crossing

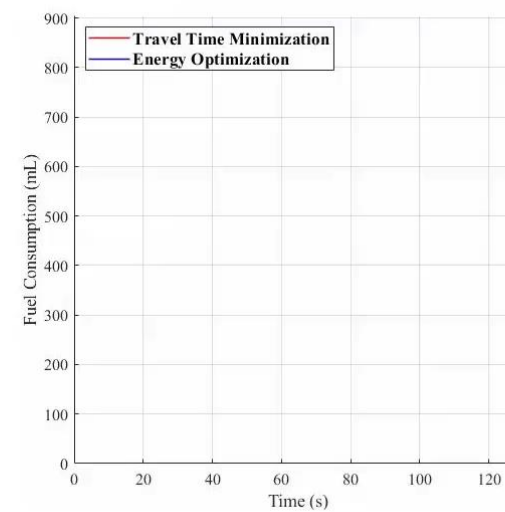
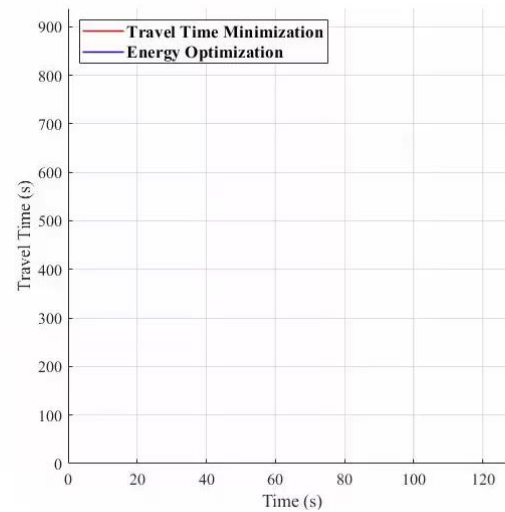
Energy Optimization



Travel Time Minimization

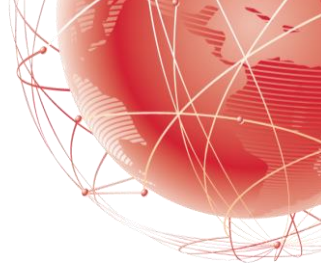


(2x speed)





Other Contributions



Other Contributions

- Traffic state estimation with bound guarantees
- Fault-tolerant traffic state estimation
- Event-based communications in public transportation systems
- Data offloading transfers through intervehicle communication transmissions
- Electric vehicle routing with charging in transportation networks using probabilistic models
- Distributed network traffic signal optimization (using I2I)
- Origin-destination matrix estimation using Bayesian theory and mathematical programming

KIOS CoE Interests and Expertise in ITS



■ Problems of interest

- Traffic control of urban and highway networks (conventional/CAVs)
- Traffic Estimation and prediction
- Fault-tolerance in traffic networks and CAVs
- Communication Protocols in CAV-rich environments
- Coordination among fully autonomous vehicles

■ Areas of expertise

- Optimization
- Control
- Fault diagnosis
- Communications



Educational Activities in ITS



Educational Activities in ITS

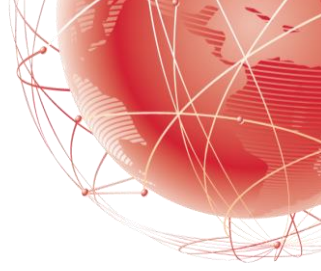
- **ECE 807: CIS Applications I – Fundamentals (6 hours)**
- **Lecture 1 (2 hours)**
 - Introduction to Intelligent Transportation Systems (ITS)
 - Monitoring Control and Security of ITS
 - Future Mobility
- **Lecture 2 (2 hours)**
 - Fundamental concepts of traffic flow theory
 - Microscopic modelling
- **Lecture 3 (2 hours)**
 - Macroscopic modelling
- **Tutorial Session (2 hours)**
 - SUMO microscopic traffic simulator
- **ITS-related Project**
 - Simulate and examine traffic phenomena in SUMO ([link to traffic flow theory](#))

Educational Activities in ITS



- **ECE 808: CIS Applications II – Advanced (6 hours)**
- **Lecture 1: Estimation and Control in Highway Networks (3 hours)**
 - Estimation of traffic state variables using KF and MHE
 - Traffic estimation in the presence of faulty measurements
 - Investigation of traffic control strategies using techniques from control and optimization
- **Lecture 2: Estimation and Control in Urban Traffic Networks (3 hours)**
 - The concept of the Macroscopic Fundamental Diagram
 - Estimation of regional parameters
 - Regional Control Strategies for Urban Traffic Networks (Route Guidance, Perimeter Control, Demand Management)
- **Tutorial Session (2 hours)**
 - How to utilize practical optimization tools for traffic estimation and control
- **ITS-related Project**
 - Traffic estimation using KF and MHE for a realistic transportation network

Educational Activities in ITS



■ Thesis Dissertations in ITS

- Practical and Research-oriented topics on monitoring and control of ITS
- Utilize traffic flow theory and mathematical theory from courses related to control, optimization and estimation
- Different types of theses: theoretical, simulation-based, experimental
- Integrate students pursuing their thesis in the KIOS ITS research group

■ Seminars in ITS

- External keynote lectures
- Internal lectures from UCY researchers

Educational Activities in ITS



- **Teaching Philosophy**
 - Apply meaningful rather than rote learning
 - Help students link traffic concepts with everyday-life examples
 - Have learning transfer in mind
 - Help students to be able to transfer what they learn in other application contexts
 - Teach state-of-the-art concepts and methods
 - Use different audiovisual means to illustrate concepts
 - Expose students to experts working in ITS
 - Help students learn state-of-practice software tools
 - Traffic simulation, optimization, estimation
 - Link theory to real-world problems



Conclusions

- Intelligent Transportation Systems is an exciting area for various engineering disciplines
- Transport is at the cusp of a **revolution** brought by electric, connected and automated vehicles, as well as shared mobility
- ITS provides great opportunities to:
 - Perform exciting research
 - Undertake a professional career
- Important to incorporate in educational activities

Thank you for listening

